

CURRICULUM VITAE



Professor Kostas Tarchanidis Ph.D.
Professor in the Department of Chemistry, School of Science,
International Hellenic University
Kavala Campus

<i>NAME:</i>	Kostas Tarchanidis
<i>FATHER's NAME:</i>	Nikolaos Tarchanidis
<i>DATE OF BIRTH:</i>	30 th of March 1964
<i>PLACE OF BIRTH:</i>	Kalohori - Kastorias - Greece
<i>ADDRESS (Kavala Campus):</i>	Department of Chemistry, School of Science, International Hellenic University Kavala Campus Ag. Loukas 65404 Kavala, Greece
<i>(HOME):</i>	Venizelou 42B Kavala, Greece
<i>TEL:</i>	0030 – 2510 – 462238 (Office)
<i>Fax:</i>	0030 – 2510 – 225858
<i>Emails:</i>	ktarch@chem.ihu.gr
<i>HOMEPAGE:</i>	http://petrotech.teikav.edu.gr/images/docs/cvs/cvtarchanidis.pdf
<i>Skype Name:</i>	ktarch1
<i>Google Scholar Citations (385 citations, h-index 8)</i>	https://scholar.google.com/citations?user=wfVVcu4AAAAJ&hl=en&oi=ao

EDUCATION

- 1989** Degree in Electrical Engineering, Dept. Electrical Eng., Engineering Faculty, Democritus University of Thrace, grade 7.86/10
- 1993** Ph.D. in Robotics ("*Kinematics for Modular Robots*"), Dept. Electrical Engineering and Electronics, Engineering Faculty, University of Liverpool

WORK EXPERIENCE

- 2/3/93-
28/2/95 Military Service: Second Lieutenant – Telecommunication Expert
- 1989 – 1998 Development of customised digital circuits - Microcontroller/ microprocessor boards.
- 1989 – 1998 Electrical Engineer – Consulting
- 1995-1998 Founder and Partner of the Lamda Inc. High Technology Applications. The company specialises in sectors like: industrial automation-Robotics, development of digital circuits, digital image processing, process control - modelling, software, telemetry and monitoring systems. It has been accredited by the Ministry of Development as high technology company.

Research Interests

- Analog – Digital circuits – Logic Design
- Microelectronics – Integrated Circuits – Microsystems
- Microcontrollers – Computer/Microcomputer Architecture
- Parallel Processing – Concurrent System Programming
- Instrumentation and Measurements (Sensors and Transducers)
- Mechatronics – Metrology
- Control Systems – Embedded Systems – Integrated Industrial Control Applications
- Robotic Systems- Design – Control – Industrial Applications
- Autonomous Systems (Vehicles – Walking/Crawling Robots etc)

Teaching Experience

- 1990-92 Lab demonstration to the 1st year students of the Engineering Science Dept. , Liverpool University – Gr. Britain
- 1995 Lecturer for “Electrical Circuits & Machines” (2nd Semester) and “Automation” (6th Semester) - Dpt of Industrial Mechanical Engineering , University of Thessaly - Greece
- 2/1997 -
2000 Lecturer for “Digital Systems and Computers I” (6th Semester) – Dpt of Electrical and Computer Engineering – Democritus University of Thrace - Greece
- 1997 Lecturer for “Mechanical Design using Computer” (2nd Semester), Dpt of Industrial Mechanical Engineering , University of Thessaly - Greece
- 1998-
2013 “Electrical Circuits” (1st semester), "Basic Electronics" (2nd Semester), "Control I" (3rd Semester.), “Control II” 4th Semester, Dept. of Petroleum & Natural Gas Technology, Kavala Institute of Technology - Greece
- 2013-2019 “Electrical Circuits-Applied Physics” , "Control", “Measurement systems”, “Mechanical and Natural Gas Building Installations”, “CAD Design Principles” , Dept. of Petroleum & Natural Gas Engineering and Mechanical Engineering, Easter Macedonia and Trace Institute of Technology – Greece
- 2014-2019 “Group Project”, M.Sc. Course, Easter Macedonia and Trace Institute of Technology – Greece

2019-Today “Physics II”, “Measurement systems in Chemical Industry”, “Embedded Systems in Chemical Industry” Department of Chemistry, International Hellenic University.

Laboratory Director :

Control Systems Technologies and Autonomous Systems (COSTAS) Laboratory

Administration Position

1. 1999 – 2001 Representative of the Assistant Professors to the Council of the Dept. of Petroleum & Natural Gas Technology – Kavala Institute of Technology
2. 2001 – 2003 Head of Department of Petroleum & Natural Gas Technology – Kavala Institute of Technology
3. 2003-2009 Dean of Engineering School – Kavala Institute of Technology
4. 2013-2016 University’s Council Vice President

COORDINATION/PARTICIPATION IN RESEARCH PROJECTS

Coordinator in 3 research Projects. Participant in 10 research projects as member of the research team.

Journal Publications

- 1 **Tarchanidis K.**, Mackay A.S, Lucas J., "Flexible Kinematics for Modular Robots" Microprocessors and Microsystems, Vol. 19, No.9, pp.525-532, 1995
- 2 I. Seftelis, S. Trasanidis, **K. Tarchanidis***, G. Bakos, N. Tsagas " Variations of gross alpha, beta air radioactivity correlated with air temperature and humidity", Hadronic Journal, Vol. 18, no. 3, pp.237-244, 1995 , (*) Corresponding author.
- 3 Lygouras J., Tsagas N., Bakos G., **Tarchanidis K.** and Tsalides P. "Remotely Operated Vehicle (ROV) Position Control by Implementation of Modern Control Theory Techniques", Modelling Measurement & Control, B, AMSE Press, Vol. 59, No.3, 1995, pp. 5-14
- 4 J.N. Lygouras, **K.N. Tarchanidis** "Non-linear circuit cancels the non-linearity of a DC motor ", Int. J. of Electronics, 1998, Vol.84, No. 2, pp 147-156
- 5 J.N. Lygouras, **K.N. Tarchanidis** "Suspended sediment and dye concentration measurements using a digital technique", Int. J. of Electronics, 2000, Vol. 87, No1, pp107-118
- 6 **Tarchanidis K.N.**, Lygouras J.N., "Data Glove with a Force Sensor", IEEE Journal of Instrumentation and Measurement, Vol. 52, Num.3, June 2003, pp. 984-989.
- 7 A. Christoforides, N. Kanellopoulos, A. Mitropoulos, K.L. Stefanopoulos and **K. Tarchanidis**, “Characterization of controlled pore glasses by small angle x-ray scattering and evaluation of the scattering data by the indirect Fourier transformation method”, CHARACTERIZATION OF POROUS SOLIDS VI -STUDIES IN SURFACE SCIENCE AND CATALYSIS,144: 769-774 2002, Elsevier,
- 8 Pachidis T., **Tarchanidis K.**, Lygouras J. and Tsalides P., “Robot Path Generation

- Method for a Welding System Based on Pseudo Stereo Visual Servo Control,” EURASIP Journal on Applied Signal Processing, Vol. 2005, No. 14, 11 August 2005
9. Lygouras J.N., Kodogiannis V.S., Pachidis Th., **Tarchanidis K.N.** and Koukourlis C.S., “Variable structure TITO fuzzy-logic controller implementation for a solar air-conditioning system”, [Applied Energy](#), [Volume 85, Issue 4](#), April 2008, Pages 190-203
 10. D. Badekas, N. Vordos, **Tarchanidis K.N.**, L. Magafas, G. Tsirigotis “Optimum Selection based on the Energy Capacity between Different Types of Renewable Sources using a Controller”, *Electronics and Electrical Engineering* 2007.No. 8(80), pp 9-12
 11. Pachidis T, Lygouras J.N. and **Tarchanidis K.N.**, “HumanPT : An Open-source, HumanPT Architecture-based, Robotic Application for Low Cost Robotic Tasks”, [Journal of Intelligent and Robotic Systems](#), [Volume 51, Number 4 / April, 2008](#), pp. 385-420
 12. Pachidis T, Lygouras J.N. and **Tarchanidis K.N.**, “Adaptive High-Performance Velocity Evaluation Based on High Resolution Time-to-Digital Converter”, *IEEE Transactions on Instrumentation and Measurements*, 57(9) 2008 , pp. 2035-2043
 13. **Tarchanidis K.N.**, Soilemes A.T., “Digitally Synthesized Alternative Current Sinusoidal Waveform for Resistive Sensor Measurements”, *Journal of Engineering Science and Technology Review* 4 (1) (2011) 50-54
 14. **Tarchanidis K.N.**, Lygouras J.N., P. Botsaris, “Voltage Stabilizer Based on SPWM technique Using Microcontroller”, *Journal of Engineering Science and Technology Review* 6 (1) (2013) 38-43
 15. **Tarchanidis K.N.**, Lygouras J.N., Pachidis Th., Tarchanidis J.N., “PUMA Internet Task Logging Using the IDAC-1”, *Journal of Engineering Science and Technology Review* 7 (3) (2014) 188– 191
 16. Lygouras E., Gasteratos A., **Tarchanidis K.N.**, Mitropoulos A., “ROLFER: A fully autonomous aerial rescue support system”, *Microprocessors and Microsystems* 61 (2018) 32–42
 17. Lygouras E., Dokas I., Andritsos K., Gasteratos A., **Tarchanidis K.**, “Identifying Hazardous Emerging Behaviors in Search and Rescue Missions with Drones: A Proposed Methodology”, *Lecture Notes in Business Information Processing*, 301 (2017), pp. 70-76
 18. Lygouras E., Gasteratos A., **Tarchanidis K.**, “ROLFER: An Innovative Proactive Platform To Reserve Swimmer’s Safety”, *Lecture Notes in Business Information Processing*, 301 (2017), pp. 57-69

Conferences

- 1 Lygouras J., Tsagas N., Bakos G., **Tarchanidis K.** and Tsalides P. "Remotely Operated Vehicle (ROV) Position Control by Implementation of Modern Control Theory Techniques", International AMSE Conference, Systems, Control & Design, SYS'94, Lyon (France), July 1994.
- 2 Bakos G. C., Tsagas N.F., Lygouras J. N, **Tarchanidis K.N.** and Micholitsis G., "Development of a Sonar System For ROV Positioning". AMSE , Intern. Confer. "Information Processing Methodologies & Applications", New Orleans (USA), Nov. 9-11 1994

- 3 **Tarchanidis K.N.**, Lygouras J.N., Sarafis I.T., "A New Residual Vector for Fast Converging Iterative Algorithm Solving the Inverse Kinematics Problem", AMSE SYS '90, July 3-5, 1995.
- 4 Lygouras J.N., **Tarchanidis K.N.**, Kakkalis J.K., Dimitriadis C. " DC motor linearisation", Workshop on Developments in Industrial Control Systems, 3-5 Oct. 1996, Thessaloniki
- 5 **Tarchanidis K.N.**, Lygouras J.N. "Communication Interface Between Transputer and the PUMA robot", ICARCV'96, Singapore 3-6 Dec. 1996
- 6 Lygouras J.N., **Tarchanidis K.N.**, Tsalides Ph., "THETIS An underwater Remotely Operated Vehicle", OCCEANS96/MTS/IEEE, 23-26 Sept. 1996, Ft. Lauderdale, Florida, USA
- 7 Lygouras J.N., **Tarchanidis K.N.** "High resolution optical suspended sediment detector" IASTED, 22 Feb. 1996, Innsbruck- Austria
- 8 **Tarchanidis K.N.**, Lygouras J.N., "A Hybrid Neural Network/ Newton-Raphson Algorithm Solving the Inverse Kinematics Problem", IASTED Int. Conference, Control and Applications (CA'2000), May 24-27, Cancun, Mexico, pp.236-245
- 9 **Tarchanidis K.N.**, Ioannidis I., Kakkalis I., Lygouras J.N., « FLEXIMAT, an Integrated System Scanning the Bedding of Any Mattress», Int. Workshop on Virtual and Intelligent Measurements Systems VIMS 2000, 29-30 April, MD, USA, pp.115-120
- 10 **Tarchanidis K.N.**, Sarafis E., Lygouras J.N., « Multisegment Snake-like Manipulator», IASTED Int. Conf. Robotics and Applications, RA2000, August 14-16 2000, Honolulu, Hawaii, USA, pp. 264-269
- 11 Sarafis E.T, **Tarchanidis K.N.**, Lygouras J.N., «**Automation of underwater tasks using an electrically driven manipulator**», Proceedings of the IASTED International Conference Robotics and Applications 2000 August 14-16, 2000 – Honolulu, Hawaii, USA, pp. 24-28
- 12 **Tarchanidis K.N.**, Lygouras J.N., "Data Glove with a Force Sensor", Proceedings of the 18th IEEE Instrumentation and Measurement Technology Conference, Budapest, 21-23 May, 2001, pp 380-385
- 13 Lygouras J.N., **Tarchanidis K.N.**, Tsalides Ph., "A Digital Optical-Fiber Finger Blood Volume Meter", Proceedings of the 18th IEEE Instrumentation and Measurement Technology Conference, Budapest, 21-23 May, 2001, pp 648-653
- 14 **Tarchanidis K.N.**, Koukourlis Ch., "Digital Alternative Sinusoidal Current Waveform for Virtual Resistance Measurements" Proceedings of the VIMS 2001, International Workshop on Virtual and Intelligent Measurement Systems, Budapest, 19-20 May, 2001, pp. 52-56
- 15 Christoforides A., Kanellopoulos N., Mitropoulos A., Stefanopoulos K.L. and **Tarchanidis K.N.**, "Characterization of controlled pore glasses by small angle x-ray scattering and evaluation of the scattering data by the indirect Fourier transformation

- method”, Proceedings of the 6th Int. Symposium on the Characterization of Porous Solids (COPS-VI), Allicante, Spain, May 8-11, 2002
16. [Tarchanidis K.N.](#), Lygouras J.N., Chatziandreoglou Ch., “Internet Task Logging Using the IDAC-1”, IWSSIP 2002, Manchester, November 7-8, 2002
 17. [Tarchanidis K.N.](#), Lygouras J.N., Chatziandreoglou Ch., “Closed Loop Control Trough Internet Using the IDAC-1”, IEEE Instrumentation and Measurement Technology Conference 2003 ,Vail, CO, USA, 20-22 May 2003
 18. [Tarchanidis K.N.](#), Pachidis T., Lygouras J.N., Koutras J.K., “Remote Robot Task Monitoring Using the IDAC-1”, IEEE Instrumentation and Measurement Technology Conference 2006, Sorento, Italy, April 2006.
 19. [Tarchanidis, K.N.](#), [Lygouras, J.N.](#), [Pachidis, T.](#), [Kodogiannis, V.](#), [Chatziandreoglou, C.G.](#) “PH neutralization through Internet”, 2006 Proceedings of 2006 IEEE International Conference on Virtual Environments, Human-Computer Interfaces and Measurement Systems, VECIMS 2006, art. no. 4016654, pp. 19-23
 20. [Pachidis, T.](#), [Tarchanidis, K.](#), [Lygouras, J.](#) “Apparatus based experimental study of physics phenomena» 2006 Proceedings of 2006 IEEE International Conference on Virtual Environments, Human-Computer Interfaces and Measurement Systems, VECIMS 2006, art. no. 4016673, pp. 102-107
 21. [Pachidis, T.](#), [Lygouras, J.](#), [Tarchanidis, K.](#), [Kodogiannis, V.](#) “HumanPT: Architecture for low cost robotic applications” 2006 Proceedings of 2006 IEEE International Conference on Virtual Environments, Human-Computer Interfaces and Measurement Systems, VECIMS 2006, art. no. 4016685, pp. 154-159
 22. Lygouras E., Dokas I., Andritsos K., Gasteratos A., [Tarchanidis K.](#), “**Identifying Hazardous Emerging Behaviors in Search and Rescue Missions with Drones: A Proposed Methodology**” 4th International Conference on Information Systems For Crisis Response and Management in Mediterranean Countries (ISCRAM), 2017
 23. Lygouras E., Gasteratos A., [Tarchanidis K.](#), “**ROLFER: An Innovative Proactive Platform To Reserve Swimmer’s Safety**” 4th International Conference on Information Systems For Crisis Response and Management in Mediterranean Countries (ISCRAM), 2017